Mechanical Workshop

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ROBOJACKETS

COMPETITIVE ROBOTICS AT GEORGIA TECH

www.robojackets.org

Open the "speaker notes" for additional info



Materials



Aluminum

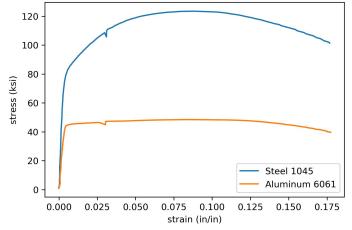
- Alloys: 6061, 7075, 5052
- Lightweight
- Pretty cheap
- Pretty strong
- Easily shaped
- Corrosion resistant
- Harder to weld



Steel

- Alloys: A36, 1045
- Stainless: 304, 316
- Very strong
- Easy to weld
- Heavy
- More expensive

Stress Strain Curve of Steel 1045 and Aluminum 6061 in tension



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Polycarbonate

- Very light
- Transparent
- Flexible, formable
- Tough
- Weaker than
 aluminum

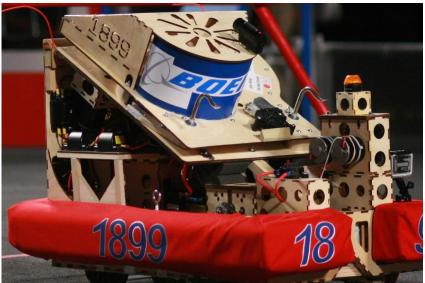




Wood

- Versatile: lumber, plywood, composites
- Light
- Cheap (theoretically)
- Easy to cut and join
- Weaker





Tools



Drill

- Create holes of various sizes
- Cordless vs corded, impact driver
- Drill bits vs driver bits



Drill Press

- Bench-mounted drill
- Makes square holes (no, not that kind of square hole)
- Clamps recommended
- Not to be used with end mills or sanding drums



Rotary Tool

- Tiny drills
- Cutting discs
- Sanding drums and grinding burs
- Always clamp workpiece



Jigsaw

- Cut complex 2D shapes
- Quick and effective
- Can be rough and imprecise



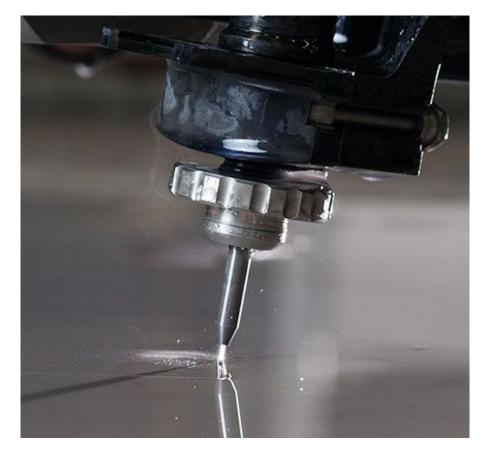
Bandsaw

- Different blades for wood and metal
- Horizontal vs. vertical
- Rip fences and miter gauges



Waterjet

- High precision, repeatable due to CAM
- Some limitations
- Available to all Georgia teams through KSU waterjet sponsor



Post-Kickoff Update

- Follow this link for "Material and Manufacturing Partnerships": <u>http://gafirst.org/for-teams/manufacturing/</u>
- It appears the waterjet sponsorship is currently on hold, but there are still other opportunities that appear to be open



Shopvac

- Clean up after yourself
- Attachments (wide, nozzle)
- Safety, aesthetic, and reputation hazard



Drivetrains



Drop Center Drive

- Most common
- Included in the Kit of Parts
- Easy to assemble, drive, and program
- Great at defense
- Nonholonomic



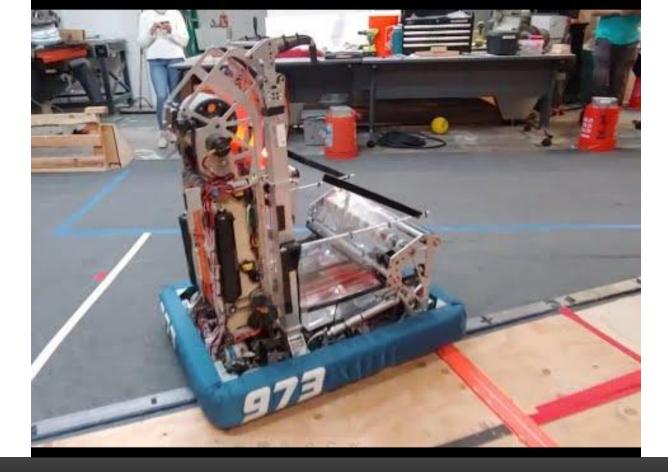


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West Coast Drive

- Pretty popular
- Mechanically very similar
- Easier maintenance
- Lighter weight
- Wheels more susceptible to damage



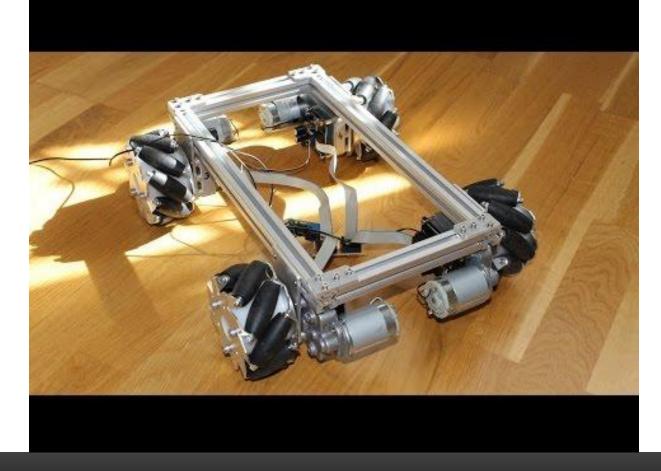


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Mecanum Drive

- Most common holonomic drivetrain
- Fairly easy to program
- Bad at defense
- Requires independent control of all four wheels

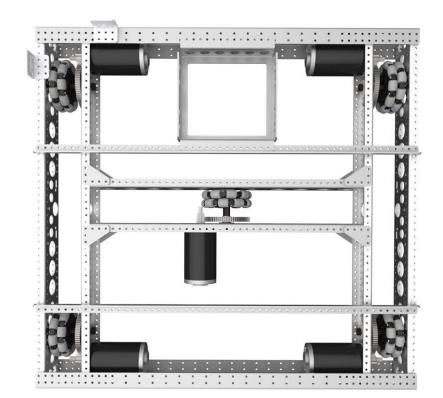




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H-Drive

- Pretty uncommon
- Just as easy to assemble
- Similar limitations (e.g. bad at defense)
- All holonomic options require skilled drivers

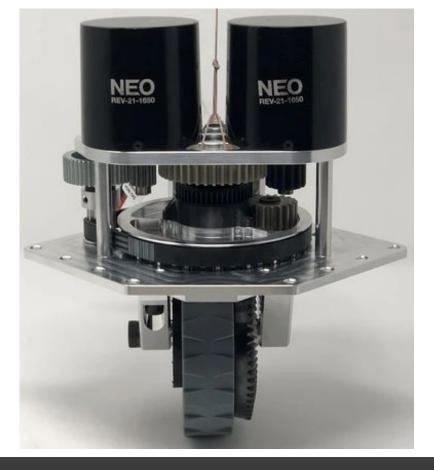




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Swerve

- Holonomic, yet good at defense
- Expensive
- Challenging to assemble and program
- High maintenance





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Question:

Which drivetrain was most popular among the 2022 FIRST Championship Einstein finalist teams?

- A. Drop Center
- B. West Coast
- C. Mecanum
- D. Swerve

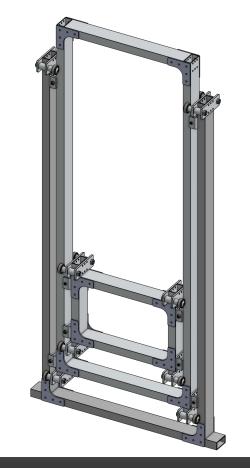
1619: Swerve1577: Swerve254: Swerve4414: Swerve3175: Swerve2539: Swerve6672: Swerve4099: Swerve

Lifts

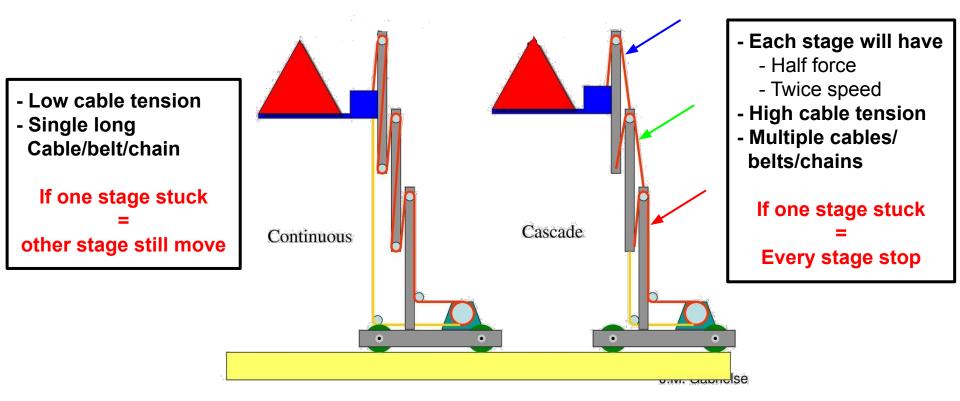


Elevator

- Most popular
- Driven by strings, pulleys, or chain
- Normally 2-stage, could be more
- The last stage normally carries the grabber/intake module.
- Elevators may need to bear the weight of the robot.



2 ways for strings & pulleys



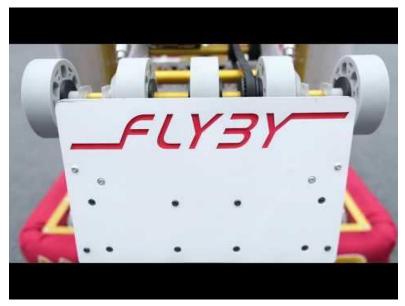
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Which method is used in the following videos?

Season: 2019 Team: 1619



Season: 2019 Team: 118

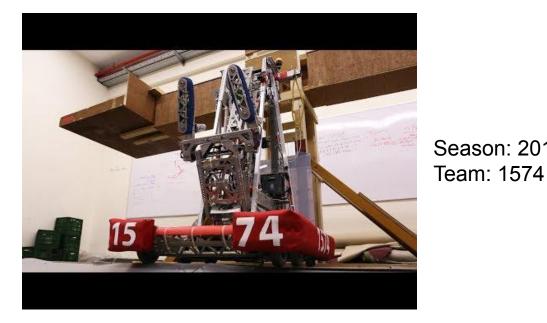


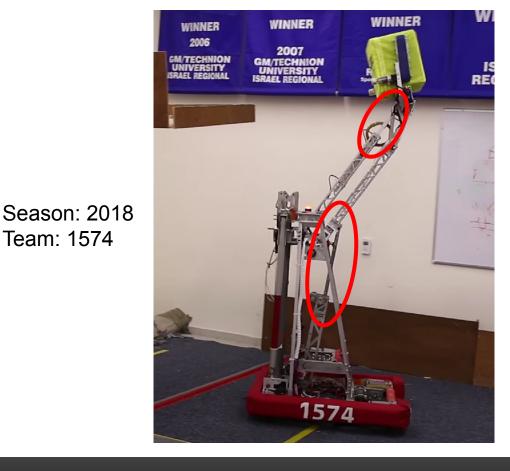
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Multi-segment arm

- Good option for elevating game pieces
- Possible but not ideal for lifting the robot
- Predicting final position is challenging
- Rotary motion vs linear
- Useful for flipping the game piece to the back side of the robot.
- Occupies a lot more space
- Difficult to maintain





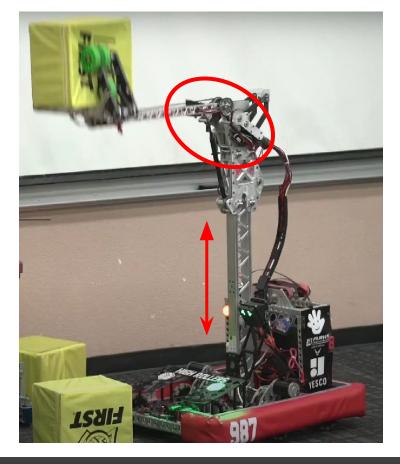


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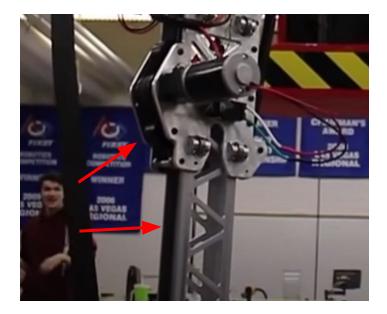
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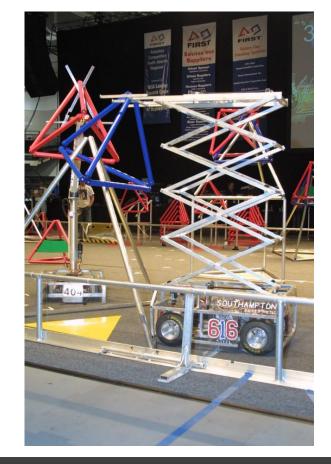
Season: 2018 Team: 987



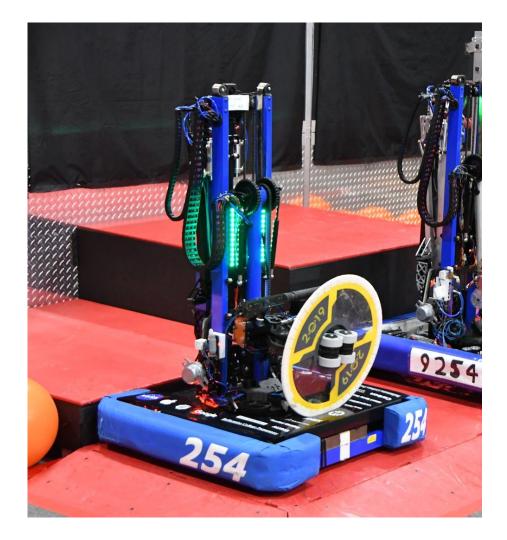
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Scissor Lift

- Much less common
- Very difficult to make right
- Requires precise dimensions
- It has very efficient motion,
- Cannot support as much weight as others
- Difficult to maintain. Not so reliable.



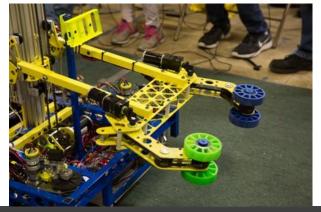
Grabbers/ Actuation



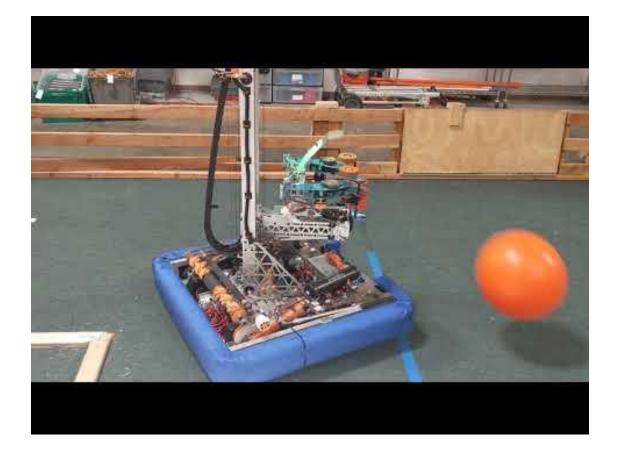
Wheels

- Broad category of devices that use wheels to move game elements
- Intakes are the most common, for balls or elements with volume
- Often, compliant (squishy) wheels are used to provide greater grip on the game elements





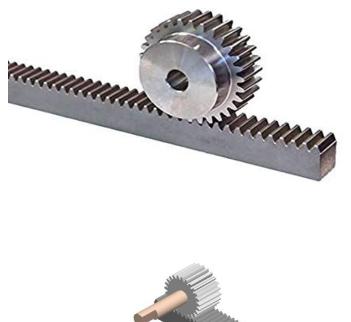
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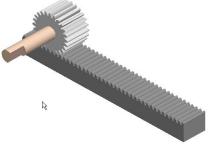


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Rack and Pinion

- Rotational motion -> linear motion
- Very simple mechanical system
- Can be used to make a linear grabber
- It is durable and likely won't break
- Can be very slow
- Can get jammed
- Made of steel, so it is heavy





Spring Loaded

- Used as a passive grabbing system
- Pressure from the object it is holding puts the springs in tension.
- The equilibrium force pushes back against object, holding it in place



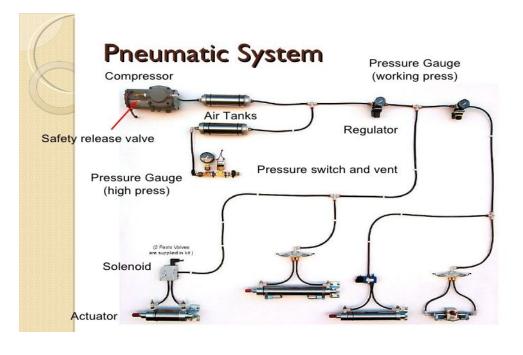
Torsion Spring

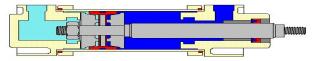


Spiral Spring

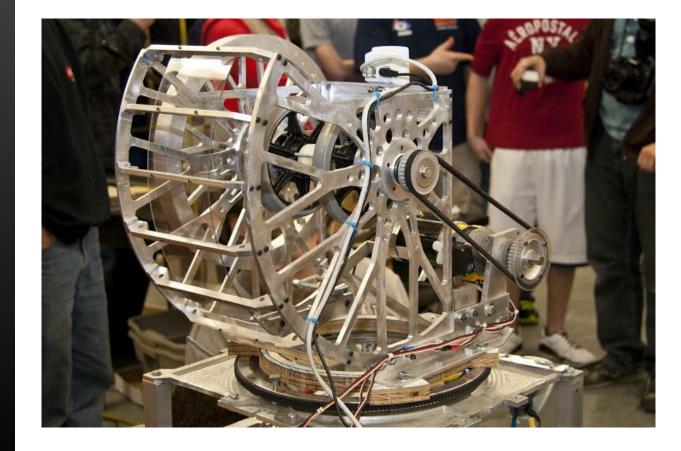
Pneumatics

- A common element on many robots, wide variety of uses
- Two-position pistons are the most common, which can be either retracted or extended
- Does not allow for granular control other than speed of extension





Shooters



Stationary Shooter

Most common variety of shooter

Pros:

Cons:

- Easiest to build
- Easiest to tune
- Fewest variables



Flywheel

Stationary Shooter



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Adjustable Hood

Improvement on top of standard stationary shooter

Pros:

- Increases range and available shooting locations of shooter
- Can shoot from very close angles

Cons:

- Difficult to tune
- Introduces more shooting variables



Team 254 "Dropshot" technical binder

Adjustable Hood



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Turreted Shooter

Improvement on top of standard stationary shooter

Pros:

 Allows shooting from multiple robot orientations Cons:

- Challenging to maintain
- Challenging to program



Team 254 "Dropshot" technical binder

Turreted Shooter



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Q&A

